

**MATLAB Course  
November-December 2006**

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- **MATLAB: Matrix Laboratory**
- The Math Work Inc.
- See “Getting Started with MATLAB, version 6”

Chapter 1: Elementary operations

Chapter 2: M-files

Chapter 3: Graphics

Chapter 4: Optimization

Chapter 5: Assignment

## MATLAB Course November-December 2006

### Chapter 1: Elementary operations

- >> place for action in Matlab command window
- **Create matrix**  $A = \begin{pmatrix} 1 & 2 & 5 & 2 \\ 7 & 2 & 4 & 5 \\ 8 & 1 & 3 & 2 \end{pmatrix}$ .  

```
>>A=[1 2 5 2;7 2 4 5;8 1 3 2]
```
- Show element  $A(1,3)$   

```
>>A(1,3)
```
- Compute sum of columns  

```
>> sum (A)
```
- Operator colon “:”,  

```
>>A(1,:)
>>A(1,2:3)
```
- Use the colon for selection of parts of matrix A  

```
>>A(1,2:3)
```
- Building blocks of expressions
  - Variables  

```
>>x=[1 -2 3]
```

, x is a (1×3) array.
  - Numbers, real, integer, complex  

```
>>x=[1:1:8]
```
  - Operators
  - Functions
- Give examples
- Operators on two matrices **A** and **B** (if sizes correct, and symmetric if necessary)
  - + sum, >>A+B
  - - difference, >>A-B
  - \* product, >>A\*B
  - / division, >>A/B is equal to  $\mathbf{AB}^{-1}$
  - \ division, >>A\B is equal to  $\mathbf{A}^{-1}\mathbf{B}$
  - ^ power >>A^3 is equal to  $\mathbf{A} \times \mathbf{A} \times \mathbf{A}$
  - ‘ transpose, >>A’
  - .^ element wise power, >>A.^2
  - .\* element wise product, >>A.\*B

- Functions:
  - abs     absolute value
  - sqrt    square route
  - exp     exponent
  - sin     sinus
  - size    dimensions of a matrix
  - inv     inverse of a matrix
  - det     determinant of a matrix

## Information about functions

Type:

For list of elementary mathematical functions

help elfun

For list of advanced mathematical and matrix functions

help specfun  
help elmat  
help matfun

For special function type:

help *function name*

For instance

>> **help zeros**

ZEROS Zeros array.

ZEROS(N) is an N-by-N matrix of zeros.

ZEROS(M,N) or ZEROS([M,N]) is an M-by-N matrix of zeros.

ZEROS(M,N,P,...) or ZEROS([M N P ...]) is an M-by-N-by-P-  
by-... array of zeros.

ZEROS(SIZE(A)) is the same size as A and all zeros.

See also EYE, ONES.

If you do not know the exact name of a function type:

lookfor ....

>> **help elfun**

**Elementary math functions.**

**Trigonometric.**

sin	- Sine.
sinh	- Hyperbolic sine.
asin	- Inverse sine.
asinh	- Inverse hyperbolic sine.
cos	- Cosine.
cosh	- Hyperbolic cosine.
acos	- Inverse cosine.
acosh	- Inverse hyperbolic cosine.
tan	- Tangent.
tanh	- Hyperbolic tangent.
atan	- Inverse tangent.
Atan2	- Four quadrant inverse tangent.
atanh	- Inverse hyperbolic tangent.
sec	- Secant.
sech	- Hyperbolic secant.
asec	- Inverse secant.
asech	- Inverse hyperbolic secant.
csc	- Cosecant.
csch	- Hyperbolic cosecant.
acsc	- Inverse cosecant.
acsch	- Inverse hyperbolic cosecant.
cot	- Cotangent.
coth	- Hyperbolic cotangent.
acot	- Inverse cotangent.
acoth	- Inverse hyperbolic cotangent.

**Exponential.**

exp	- Exponential.
log	- Natural logarithm.
log10	- Common (base 10) logarithm.
log2	- Base 2 logarithm and dissect floating point number.
pow2	- Base 2 power and scale floating point number.
realpow	- Power that will error out on complex result.
reallog	- Natural logarithm of real number.
realsqrt	- Square root of number greater than or equal to zero.
sqrt	- Square root.
nextpow2	- Next higher power of 2.

**Complex.**

abs	- Absolute value.
angle	- Phase angle.
complex	- Construct complex data from real and imaginary parts.
conj	- Complex conjugate.

imag	- Complex imaginary part.
real	- Complex real part.
unwrap	- Unwrap phase angle.
isreal	- True for real array.
cplxpair	- Sort numbers into complex conjugate pairs.

### **Rounding and remainder.**

fix	- Round towards zero.
floor	- Round towards minus infinity.
ceil	- Round towards plus infinity.
round	- Round towards nearest integer.
mod	- Modulus (signed remainder after division).
rem	- Remainder after division.
sign	- Signum.

>> **help specfun**

### **Specialized math functions.**

#### **Specialized math functions**

airy	- Airy functions.
besselj	- Bessel function of the first kind.
bessely	- Bessel function of the second kind.
besselh	- Bessel functions of the third kind (Hankel function).
besseli	- Modified Bessel function of the first kind.
besselk	- Modified Bessel function of the second kind.
beta	- Beta function.
betainc	- Incomplete beta function.
betaln	- Logarithm of beta function.
ellipj	- Jacobi elliptic functions.
ellipke	- Complete elliptic integral.
erf	- Error function.
erfc	- Complementary error function.
erfcx	- Scaled complementary error function.
erfinv	- Inverse error function.
expint	- Exponential integral function.
gamma	- Gamma function.
gammainc	- Incomplete gamma function.
gammaln	- Logarithm of gamma function.
psi	- Psi (polygamma) function.
legendre	- Associated Legendre function.
cross	- Vector cross product.
dot	- Vector dot product.

**Number theoretic functions.**

factor	- Prime factors.
isprime	- True for prime numbers.
primes	- Generate list of prime numbers.
gcd	- Greatest common divisor.
lcm	- Least common multiple.
rat	- Rational approximation.
rats	- Rational output.
perms	- All possible permutations.
nchoosek	- All combinations of N elements taken K at a time.
factorial	- Factorial function.

**Coordinate transforms.**

cart2sph	- Transform Cartesian to spherical coordinates.
cart2pol	- Transform Cartesian to polar coordinates.
pol2cart	- Transform polar to Cartesian coordinates.
sph2cart	- Transform spherical to Cartesian coordinates.
hsv2rgb	- Convert hue-saturation-value colors to red-green-blue.
rgb2hsv	- Convert red-green-blue colors to hue-saturation-value.

>> **help elmat**

**Elementary matrices and matrix manipulation.****Elementary matrices.**

zeros	- Zeros array.
ones	- Ones array.
eye	- Identity matrix.
repmat	- Replicate and tile array.
rand	- Uniformly distributed random numbers.
randn	- Normally distributed random numbers.
linspace	- Linearly spaced vector.
logspace	- Logarithmically spaced vector.
freqspace	- Frequency spacing for frequency response.
meshgrid	- X and Y arrays for 3-D plots.
:	- Regularly spaced vector and index into matrix.

**Basic array information.**

size	- Size of array.
length	- Length of vector.
ndims	- Number of dimensions.
numel	- Number of elements.
disp	- Display matrix or text.
isempty	- True for empty array.
isequal	- True if arrays are numerically equal.
isequalwithequalnans	- True if arrays are numerically equal.
isnumeric	- True for numeric arrays.

- islogical - True for logical array.
- logical - Convert numeric values to logical.

**Matrix manipulation.**

- cat - Concatenate arrays.
- reshape - Change size.
- diag - Diagonal matrices and diagonals of matrix.
- blkdiag - Block diagonal concatenation.
- tril - Extract lower triangular part.
- triu - Extract upper triangular part.
- fliplr - Flip matrix in left/right direction.
- flipud - Flip matrix in up/down direction.
- flipdim - Flip matrix along specified dimension.
- rot90 - Rotate matrix 90 degrees.
- :
- find - Find indices of nonzero elements.
- end - Last index.
- sub2ind - Linear index from multiple subscripts.
- ind2sub - Multiple subscripts from linear index.

**Multi-dimensional array functions.**

- ndgrid - Generate arrays for N-D functions and interpolation.
- permute - Permute array dimensions.
- ipermute - Inverse permute array dimensions.
- shiftdim - Shift dimensions.
- circshift - Shift array circularly.
- squeeze - Remove singleton dimensions.

**Special variables and constants.**

- ans - Most recent answer.
- eps - Floating point relative accuracy.
- realmax - Largest positive floating point number.
- realmin - Smallest positive floating point number.
- pi - 3.1415926535897....
- i, j - Imaginary unit.
- inf - Infinity.
- NaN - Not-a-Number.
- isnan - True for Not-a-Number.
- isinf - True for infinite elements.
- isfinite - True for finite elements.
- why - Succinct answer.

**Specialized matrices.**

- compan - Companion matrix.
- gallery - Higham test matrices.
- hadamard - Hadamard matrix.
- hankel - Hankel matrix.
- hilb - Hilbert matrix.

invhilb	- Inverse Hilbert matrix.
magic	- Magic square.
pascal	- Pascal matrix.
rosser	- Classic symmetric eigenvalue test problem.
toeplitz	- Toeplitz matrix.
vander	- Vandermonde matrix.
wilkinson	- Wilkinson's eigenvalue test matrix.

>> **help matfun**

### **Matrix functions - numerical linear algebra.**

#### **Matrix analysis.**

norm	- Matrix or vector norm.
normest	- Estimate the matrix 2-norm.
rank	- Matrix rank.
det	- Determinant.
trace	- Sum of diagonal elements.
null	- Null space.
orth	- Orthogonalization.
rref	- Reduced row echelon form.
subspace	- Angle between two subspaces.

#### **Linear equations.**

\ and /	- Linear equation solution; use "help slash".
inv	- Matrix inverse.
rcond	- LAPACK reciprocal condition estimator
cond	- Condition number with respect to inversion.
condest	- 1-norm condition number estimate.
normest1	- 1-norm estimate.
chol	- Cholesky factorization.
cholinc	- Incomplete Cholesky factorization.
lu	- LU factorization.
luinc	- Incomplete LU factorization.
qr	- Orthogonal-triangular decomposition.
lsqnonneg	- Linear least squares with nonnegativity constraints.
pinv	- Pseudoinverse.
lscov	- Least squares with known covariance.

#### **Eigenvalues and singular values.**

eig	- Eigenvalues and eigenvectors.
svd	- Singular value decomposition.
gsvd	- Generalized singular value decomposition.
eigs	- A few eigenvalues.
svds	- A few singular values.
poly	- Characteristic polynomial.
polyeig	- Polynomial eigenvalue problem.
condeig	- Condition number with respect to eigenvalues.



hess - Hessenberg form.  
qz - QZ factorization for generalized eigenvalues.  
schur - Schur decomposition.

**Matrix functions.**

expm - Matrix exponential.  
logm - Matrix logarithm.  
sqrtm - Matrix square root.  
funm - Evaluate general matrix function.

**Factorization utilities**

qrdelete - Delete a column or row from QR factorization.  
qrinsert - Insert a column or row into QR factorization.  
rsf2csf - Real block diagonal form to complex diagonal form.  
cdf2rdf - Complex diagonal form to real block diagonal form.  
balance - Diagonal scaling to improve eigenvalue accuracy.  
planerot - Givens plane rotation.  
Cholupdate - rank 1 update to Cholesky factorization.  
qrupdate - rank 1 update to QR factorization.



## Exercises Chapter 1

1: Generate two matrices **A** and **B** of order (5 x 5), in which matrix **A** is a symmetric matrix, and

1a: compute **A + B**, **A - B**, **AB**.

1b: compute the determinant of **A**.

1c: compute the inverse of **A** and verify that this inverse is correct.

1d: compute the eigenvalues and eigenvectors of matrix **A**.

1e: Generate a matrix **C** of order (6 x 3) and compute the singular value decomposition (svd) of **C**. Verify that this decomposition is correct by comparing the results with the eigenvectors and eigenvalues of **C'C** and **CC'**.

2: The scores of 5 subjects are given in matrix **X** for the independent variables and for the dependent variable in vector **y**..

$$\mathbf{y} = \begin{pmatrix} 10 \\ 20 \\ 17 \\ 12 \\ 11 \end{pmatrix} \text{ and } \mathbf{X} = \begin{pmatrix} 1 & 6 & 28 \\ 1 & 12 & 40 \\ 1 & 10 & 32 \\ 1 & 8 & 36 \\ 1 & 9 & 34 \end{pmatrix}.$$

2a: Estimate the regression weights in a multiple regression with  $\mathbf{y} = \mathbf{X}\mathbf{b} + \mathbf{e}$ . Here it holds:  $\hat{\mathbf{b}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$ .

2b: Compute the vector of errors and the variance of the errors.

2c: Compute the eigenvectors **V** and the eigenvalues **D** of **X'X**. Next compute  $(\mathbf{VDV}')^{-1}$  and compare this with  $(\mathbf{X}'\mathbf{X})^{-1}$ .

2d: Compute  $(\mathbf{X}'\mathbf{X})^2$  and  $\mathbf{VD}^2\mathbf{V}'$  and compare them.

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3: The scores of 4 subjects on two variables are given in the following matrix.

$$\mathbf{X} = \begin{pmatrix} 2 & 5 \\ 5 & 5 \\ 2 & 4 \\ 3 & 2 \end{pmatrix}.$$

- 3a: Transform this matrix into a matrix in which the scores are in deviations of the column means.
- 3b: Compute the covariance matrix (divide by  $n$ ) and apply the MATLAB function `cov` to  $\mathbf{X}$ . Can you explain the difference in results?
- 3c: Compute the standardized  $\mathbf{X}$ -scores (means 0 and variances 1) and place them in  $\mathbf{Z}$ .
- 3d: Compute the correlation matrix of the  $\mathbf{X}$ -scores by applying the MATLAB function `corrcoef` to  $\mathbf{X}$  and compare it with the covariance matrix of  $\mathbf{Z}$  (divided by  $n$ ).
- 3e: Carry out a principal component analysis on this correlation matrix and show the eigenvectors  $\mathbf{V}$ , the eigenvalues  $\mathbf{D}$  and the component scores  $\mathbf{ZV}$ . Are the component scores standardized?
- 3f: Compute the component loadings, which are the correlations between  $\mathbf{Z}$  and the component scores. Compare the component loadings with  $\mathbf{V}'\mathbf{D}^{1/2}$ . Why are they similar?
- 3g: Apply the function `corrcoef` to  $[\mathbf{Z}, \mathbf{Z}*\mathbf{V}]$ . Do you find the component loadings? What does the other blocks mean?